

Uniqueness of Weak Solutions to the Ricci Flow and Topological Applications

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(based on joint work with Bruce Kleiner, NYU)

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Structure of Course

- ① **Introduction:** Preliminaries + Background on Ricci flow, Blow-up analysis of singularities, Precise statement of the main results
- ② **Analytical aspects I:** Local stability analysis
- ③ **Analytical aspects II:** Comparing singular Ricci flows, Proof of the uniqueness and stability result
- ④ **Topological aspects:** Continuous families of singular Ricci flows, Proof of the topological applications

Analytic result:

- Given any closed (M^3, g) , there is a unique/canonical, weak Ricci flow “through singularities” $\mathcal{M}^{(M, g)}$ starting from (M, g) .
- This flow depends continuously on g .

Topological applications:

- For any closed M^3 , the space $\text{Met}_{PSC}(M)$ of Riemannian metrics with positive scalar curvature is either empty or contractible.
- $\text{Diff}(S^3/\Gamma) \simeq \text{Isom}(S^3/\Gamma)$
- $\text{Diff}(M) \simeq \text{Isom}(M)$ if M is hyperbolic
- similar results if $M = S^2 \times S^1$, infranil, etc.

(based on joint work with Bruce Kleiner)

Lecture I

- A Statement of the topological results
- B Ricci flow, Motivation, Singularity analysis, RF with surgery
- C Singular Ricci flows, Statement of the main uniqueness result

Lecture I.A

Statement of the topological results

Basic definitions

M (mostly) 3-dimensional, compact, orientable manifold

Recall: The topology of 3-manifolds is sufficiently well understood due to the resolution of the Poincaré and Geometrization Conjectures by Perelman, using Ricci flow.

Main objects of study:

- $\text{Met}(M)$: space of Riemannian metrics on M
- $\text{Met}_{PSC}(M) \subset \text{Met}(M)$: subset of metrics with positive scalar curvature
- $\text{Diff}(M)$: space of diffeomorphisms $\phi : M \rightarrow M$

... each equipped with the C^∞ -topology.

Goal: Classify these spaces up to homotopy (using Ricci flow)!

$\text{Met}(M)$ is contractible

Main Result 1:

Ba., Kleiner 2019

$\text{Met}_{PSC}(M)$ is either contractible or empty.

History:

- true in dimension 2 (via Uniformization Theorem or Ricci flow (see later))
- Hitchin 1974; Gromov, Lawson 1984; Botvinnik, Hanke, Schick, Walsh 2010: Further examples with $\pi_i(\text{Met}_{PSC}(M^n)) \neq 1$ for certain (large) i, n .
- Marques 2011 (using Ricci flow with surgery):
 $\text{Met}_{PSC}(M^3)/\text{Diff}(M^3)$ is path-connected,
 $\text{Met}_{PSC}(S^3)$ is path-connected

Diffeomorphism groups

Smale 1958: $O(3) \simeq \text{Diff}(S^2)$

Smale Conjecture: $O(4) \simeq \text{Diff}(S^3)$

proven by Hatcher in 1983

For a general spherical space form $M = S^3/\Gamma$ consider the injection

$$\text{Isom}(M) \longrightarrow \text{Diff}(M)$$

Generalized Smale Conjecture

This map is a homotopy equivalence.

- Verified for a handful of other spherical space forms, but open e.g. for $\mathbb{R}P^3$.
- All proofs so far are purely topological and technical. No uniform treatment.

Main Result 2:

Theorem (Ba., Kleiner 2019)

The Generalized Smale Conjecture is true.

Remarks:

- Proof via Ricci flow (first purely topological application of Ricci flow since Perelman's work \sim 15 years ago).
- Uniform treatment of all cases.
- Alternative proof in the S^3 -case (Smale Conjecture).
- There are two proofs:
 - "Short" proof (Ba., Kleiner 2017): GSC if $M \not\approx S^3, \mathbb{R}P^3$, M hyperbolic, assuming the Smale Conjecture for S^3
 - Long proof (Ba., Kleiner 2019): full GSC and $S^2 \times \mathbb{R}$ -cases

Similar techniques imply results in non-spherical case:

- If M is closed and hyperbolic, then $\text{Isom}(M) \simeq \text{Diff}(M)$.
(topological proof by Gabai 2001)
- If (M, g) is aspherical and geometric and g has maximal symmetry, then $\text{Isom}(M) \simeq \text{Diff}(M)$.
(new in non-Haken infranil case)
- $\text{Diff}(S^2 \times S^1) \simeq O(2) \times O(3) \times \Omega O(3)$
(topological proof by Hatcher)
- $\text{Diff}(\mathbb{R}P^3 \# \mathbb{R}P^3) \simeq O(1) \times O(3)$
(topological proof by Hatcher)

Connection between $\text{Diff}(M) \longleftrightarrow \text{Met}(M)$

Lemma

For any $g \in \text{Met}_{K \equiv \pm 1}(M)$:

$$\text{Isom}(M, g) \simeq \text{Diff}(M) \iff \text{Met}_{K \equiv \pm 1}(M) \text{ contractible}$$

Proof: Fiber bundle

$$\begin{aligned} \text{Isom}(M, g) &\longrightarrow \text{Diff}(M) \longrightarrow \text{Met}_{K \equiv \pm 1}(M) \\ &\phi \longmapsto \phi^* g \end{aligned}$$

Apply long exact homotopy sequence:

$$\begin{aligned} 0 &= \pi_{i+1}(\text{Met}_{K \equiv \pm 1}(M)) \\ &\longrightarrow \pi_i(\text{Isom}(M, g)) \longrightarrow \pi_i(\text{Diff}(M)) \longrightarrow \pi_i(\text{Met}_{K \equiv \pm 1}(M)) = 0 \end{aligned}$$

This reduces both results to:

Theorem (Ba., Kleiner 2019)

$\text{Met}_{PSC}(M)$ and $\text{Met}_{K \equiv \pm 1}(M)$ are each either contractible or empty.

Lecture I.B

Ricci flow, Motivation, Singularity analysis, RF with surgery

Ricci flow equation $(M, g(t)), \quad t \in [0, T)$

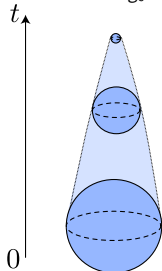
$$\partial_t g(t) = -2 \operatorname{Ric}_{g(t)}, \quad g(0) = g_0 \quad (*)$$

(in harmonic) coordinates: “ $\partial_t g_{ij} = \Delta g_{ij} + \dots$ ”

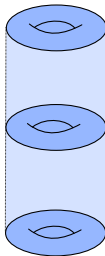
Hamilton 1982

- (*) has a unique solution $(g(t))_{t \in [0, T)}$ for maximal $T \in (0, \infty]$.
- If $T < \infty$, then “ $g(t)$ develops a singularity at time T ”, i.e. the curvature $|\operatorname{Rm}|$ blows up as $t \nearrow T$.

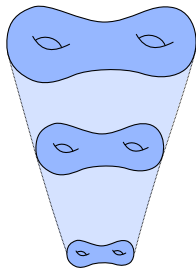
Example: If $\operatorname{Ric}_{g_0} = \lambda g_0$, then $g(t) = (1 - 2\lambda t)g_0$.



$\lambda > 0$



$\lambda = 0$



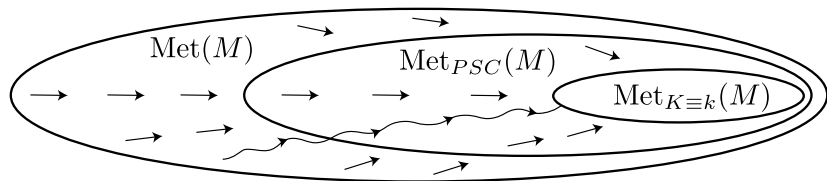
$\lambda < 0$

Ricci flow in 2D

Hamilton, Chow: On $M = S^2$ for any initial condition g_0 we have

$$T = \frac{\text{vol}(S^2, g_0)}{8\pi}, \quad (T - t)^{-1}g(t) \longrightarrow g_{\text{ground}}$$

Interpretation on the space of metrics:



- Preservation of positive scalar curvature (in all dimensions)
- \rightsquigarrow deformation retractions from $\text{Met}(S^2)$ and $\text{Met}_{PSC}(S^2)$ onto $\text{Met}_{K \equiv 1}(S^2)$

Theorem

$\text{Met}_{PSC}(S^2) \simeq \text{Met}_{K \equiv 1}(S^2) \simeq \text{Met}(S^2) \simeq *$
Therefore $\text{Diff}(S^2) \simeq O(3)$.

Difficulties:

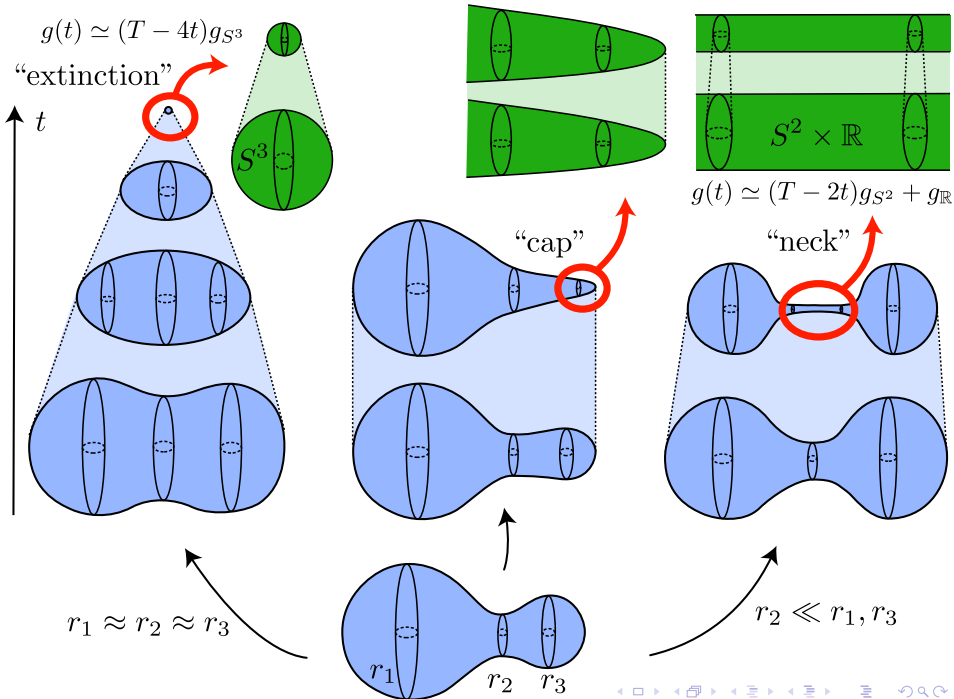
- Flow may incur non-round and non-global singularities.
- Necessary to extend the flow past the first singular time (surgeries).
- Continuous dependence on initial data?

Key analytical result:

Theorem (Ba., Kleiner, 2016)

Any (compact) 3-dimensional (M^3, g) can be evolved into a **unique** (canonical), weak Ricci flow defined for all $t \geq 0$ that “flows through singularities” and we have continuous dependence on the initial data.

Example: rotationally symmetric dumbbell



General case (no rotational symmetry):

Perelman 2002, very imprecise form

“These are (essentially) all 3D singularities”

To make this statement more precise, we have to discuss:

- the No Local Collapsing Theorem
- geometric convergence of RFs (blow-up analysis of singularities \rightarrow singularity models)
- (qualitative) classification of singularity models

No Local Collapsing

Consider a general Ricci flow $(M^n, (g_t)_{t \in [0, T)})$

Goal: “Rule out $\approx S^1(\varepsilon) \times \Sigma^{n-1}$ -singularity models”

No Local Collapsing Theorem (Perelman 2002)

There is a constant $\kappa(n, T, g_0) > 0$ such that $(M^n, (g_t)_{t \in [0, T)})$ is κ -noncollapsed at scales < 1 , i.e.:

For any $(x, t) \in M \times [0, T)$ and $r \in (0, 1)$:

$$|\text{Rm}|(\cdot, t) < r^{-2} \quad \text{on} \quad B(x, t, r) \quad \implies \quad |B(x, t, r)|_t \geq \kappa r^n$$

Corollary

$$|\text{Rm}|(\cdot, t) < r^{-2} \quad \text{on} \quad B(x, t, r) \quad \implies \quad \text{inj}(x, t) > c(\kappa)r^n$$

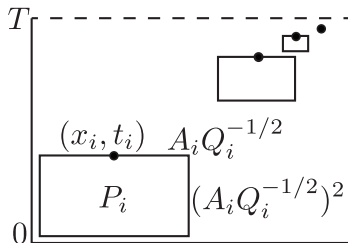
Blow-up analysis

Choose $(x_i, t_i) \in M \times [0, T]$ s.t.:

- $Q_i := |\text{Rm}|(x_i, t_i) \rightarrow \infty$
- For some $A_i \rightarrow \infty$ we have:

$$|\text{Rm}| \leq CQ_i \quad \text{on} \quad P_i = P(x_i, t_i, A_i Q_i^{-1/2})$$

where $P(x, t, r) = B(x, t, r) \times [t - r^2, t]$
 (“parabolic ball”)



Parabolic rescaling: $g_t^i := Q_i g_{Q_i^{-1}t+t_i}$

- Defined for $t \in [-Q_i t_i, 0]$, where $Q_i t_i \rightarrow \infty$
- $|\text{Rm}| \leq C$ on $P(x_i, 0, A_i)$
- NLC $\implies \text{inj}(x_i, 0) > c > 0$

After passing to a subsequence:

$$(M, g_0^i, x_i) \xrightarrow[i \rightarrow \infty]{C^\infty - CG} (\bar{M}, \bar{g}, \bar{x})$$

i.e. \exists diffeomorphisms onto their images $\psi_i : B^{\bar{M}}(\bar{x}, 0, A'_i) \rightarrow M_i$,

$\psi_i(\bar{x}) = x_i, A'_i \rightarrow \infty$ s.t.

$$\psi_i^* g_0^i \xrightarrow[i \rightarrow \infty]{C_{loc}^\infty} \bar{g}$$

$$(M, g_0^i, x_i) \xrightarrow{i \rightarrow \infty} (\bar{M}, \bar{g}, \bar{x})$$

i.e. \exists diffeomorphisms onto their images $\psi_i : B^{\bar{M}}(\bar{x}, 0, A'_i) \rightarrow M_i$,
 $\psi_i(\bar{x}) = x_i, A'_i \rightarrow \infty$ s.t.

$$\psi_i^* g_0^i \xrightarrow{i \rightarrow \infty} \bar{g}$$

Using $|\text{Rm}| < C$ on $P(x_i, 0, A_i)$, we can show that $|\partial^m \psi_i^* g_t^i|$ are locally uniformly bounded for all i . So after passing to a subsequence

$$\psi_i^* g_t^i \xrightarrow{i \rightarrow \infty} \bar{g}_t,$$

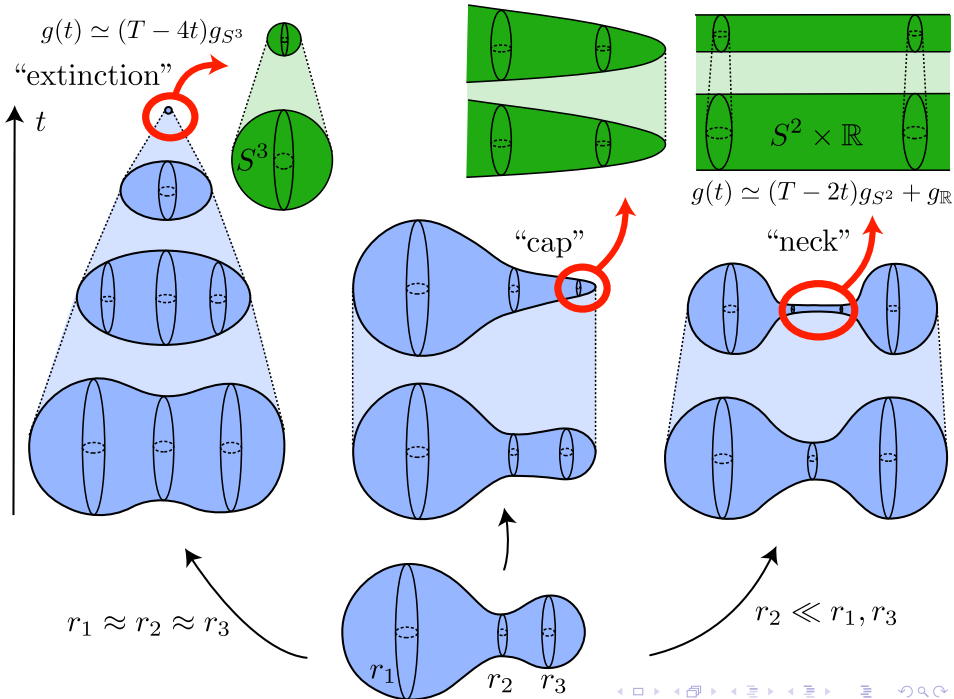
where $(\bar{g}_t)_{t \in (-\infty, 0]}$ is an **ancient Ricci flow** with $\bar{g}_0 = \bar{g}$.

Hamilton's convergence of RFs

For a subsequence

$$(M, (g_t^i)_{t \in [-t_i, Q_i, 0]}, x_i) \xrightarrow{i \rightarrow \infty} (\bar{M}, (\bar{g}_t)_{t \in (-\infty, 0]}, \bar{x})$$

" $(\bar{M}, (\bar{g}_t)_{t \in (-\infty, 0]}, \bar{x})$ models the flow near (x_i, t_i) for large i "



General case (no rotational symmetry):

Perelman 2002, version 2

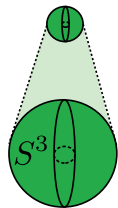
All blow-up models $(\bar{M}, (\bar{g}_t)_{t \in (-\infty, 0]})$ of $(M, (g_t)_{t \in [0, T)})$ are κ -solutions.

κ -**solution:** ancient flow $(\bar{M}, (\bar{g}_t)_{t \in (-\infty, 0]})$ s.t.

- $\text{sec} \geq 0$, $R > 0$, $|\text{Rm}| < C$ on $\bar{M} \times (-\infty, 0]$
- κ -noncollapsed at all scales:
 $|\text{Rm}| < r^{-2}$ on $B(x, t, r) \implies |B(x, t, r)|_t \geq \kappa r^3$

Qualitative classification of κ -solutions (after Perelman)

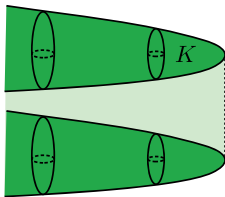
“extinction”



$$\bar{M} \approx S^3 / \Gamma$$

round if $\Gamma \neq 1, \mathbb{Z}_2$
 otherwise, possibly
 ellipsoidal

“cap”



$$\bar{M} \approx \mathbb{R}^3$$

$\bar{M} - K \approx S^2 \times (0, \infty)$
 cylindrical near ∞

“neck”



$$\bar{M} \approx S^2 \times \mathbb{R} / \Gamma$$

$\bar{g}_t = -2tg_{S^2} + g_{\mathbb{R}}$
 $\Gamma = 1, \mathbb{Z}_2$

Example in “cap” case: Bryant soliton $(M_{Bry}, (g_{Bry,t})_{t \in \mathbb{R}}, x_{Bry})$

$$M_{Bry} = \mathbb{R}^3, x_{Bry} = 0$$

$$g_{Bry,t} = dr^2 + f_t^2(r)g_{S^2}$$

$$f_t(r) \sim \sqrt{r} \quad \text{as} \quad r \rightarrow \infty$$

steady soliton equation: $\text{Ric} = \nabla^2 f = \mathcal{L}_{\frac{1}{2}\nabla f} g \implies g_{Bry,t} = \Phi_t^* g_{Bry,0}$

Brendle 2011

κ -solution + steady soliton \implies homothetic to the Bryant soliton.

Hamilton + Brendle

$\partial_t R(x, t) \geq 0$ on any κ -solution $(\bar{M}, (g_t))$

Equality \implies steady soliton

$\implies (\bar{M}, (g_t), x)$ homothetic to $(M_{Bry}, (g_{Bry,t}), x_{Bry})$

Brendle, Angenent, Daskalopoulos, Sesum, Kleiner, Ba. \sim 2019

Every κ -solution is homothetic to a quotient of the round sphere, cylinder, the Bryant soliton or Perelman's ellipsoid.

(Not needed for Uniqueness Theorem)

Singularity analysis, reworded

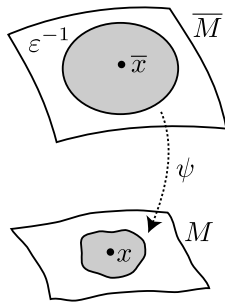
(M, g) Riemannian manifold, $x \in M$ point

- curvature scale: $\rho(x) = (\frac{1}{3}R(x))^{-1/2}$
- $(\overline{M}, \overline{g}, \overline{x})$ pointed Riem. manifold (model space)
- $(\overline{M}, \overline{g}, \overline{x})$ local ε -model at x if there is a diffeo onto its image

$$\psi : B(\overline{x}, \varepsilon^{-1}) \rightarrow M$$

such that $\psi(\overline{x}) = x$ and

$$\|\rho^{-2}(x)\psi^*g - \overline{g}\|_{C^{[\varepsilon^{-1}]}} < \varepsilon.$$



$(M, (g_t)_{t \in [0, T)})$ Ricci flow

- ... satisfies ε -canonical neighborhood assumption at scales $< r_0$ if all (x, t) with $\rho(x, t) < r_0$ are locally ε -modeled on the final time-slice $(\overline{M}, \overline{g}_0, \overline{x})$ of a pointed κ -solution.

Perelman 2002, version 3

$(M, (g_t)_{t \in [0, T)})$ satisfies the ε -canonical nbhd assumption at scales $< r(\varepsilon)$.

Ricci flow with surgery

Ricci flow with surgery:

$$\begin{aligned} (M_1, g_t^1), t \in [0, T_1], \\ (M_2, g_t^2), t \in [T_1, T_2], \\ (M_3, g_t^3), t \in [T_2, T_3], \dots \end{aligned}$$

transition maps

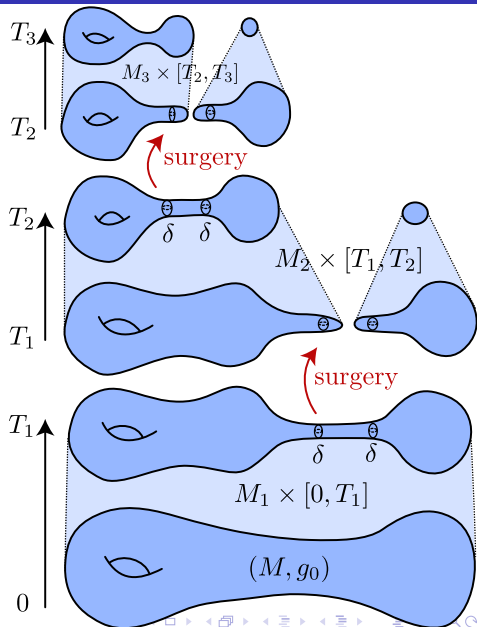
$$U_i^- \subset M_i \quad U_i^+ \subset M_{i+1}$$

$$\varphi_i : (U_i^-, g_{T_i}^i) \xrightarrow{\cong} (U_i^+, g_{T_i}^{i+1})$$

surgery scale $\approx \delta \ll 1$

Theorem (Perelman 2003)

This process can be continued indefinitely.
No accumulation of T_i .



If this flow goes extinct in finite time, then $M \approx \#S^3/\Gamma_i \#k(S^2 \times S^1)$:

Poincaré Conjecture (Perelman 2003)

$$\pi_1(M) = 1 \implies M \approx S^3.$$

If this flow exists for all times, then for $t \gg 1$:

$$M = M_{\text{thick}}(t) \cup M_{\text{thin}}(t)$$

$g(t) \simeq -4t g_{\text{hyperbolic}}$ collapsing along S^1, T^2, S^2 fibers

Geometrization Conjecture (Perelman 2003)

Every closed 3-manifold can be cut along embedded, incompressible copies of S^2, T^2 into pieces, which admit a homogeneous geometry.

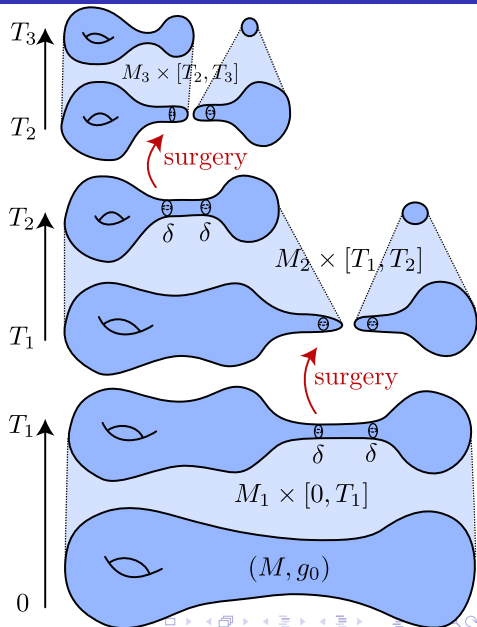
Ricci flow with surgery

Drawback:

surgery process is not canonical
(depends on surgery parameters)

Perelman:

- *It is likely that [...] one would get a canonically defined Ricci flow through singularities, but at the moment I don't have a proof of that.*
- *Our approach [...] is aimed at eventually constructing a canonical Ricci flow, [...] - a goal, that has not been achieved yet in the present work.*



Lecture I.C

Singular Ricci flows, Statement of the main uniqueness result

“Perelman’s Conjecture is true”:

- There is a reasonable definition of weak Ricci flows “through singularities”.
- We have existence and uniqueness within this class.

Comparison with Mean Curvature Flow:

- Existence of weak flows “through singularities”:
Level Set Flow, Brakke Flow
- General case: fattening \cong non-uniqueness
- Mean convex case: non-fattening \cong uniqueness
- 2-convex case: uniqueness + weak flow is limit of MCFs with surgery as surgery scale $\delta \rightarrow 0$

Ricci flow with surgery

Ricci flow with surgery:

$$\begin{aligned}(M_1, g_t^1), t \in [0, T_1], \\ (M_2, g_t^2), t \in [T_1, T_2], \\ (M_3, g_t^3), t \in [T_2, T_3], \dots\end{aligned}$$

transition maps

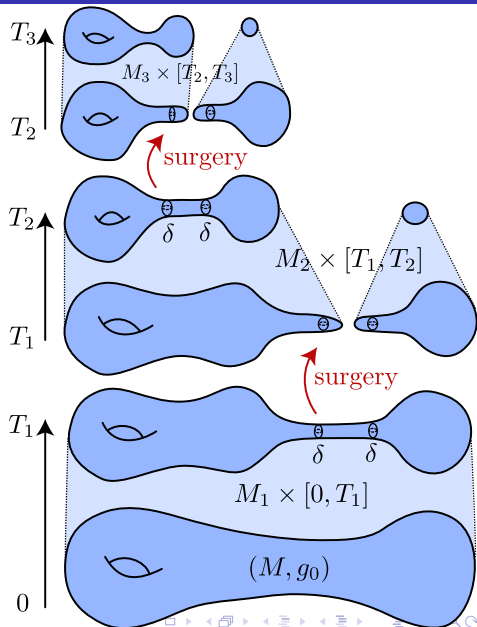
$$U_i^- \subset M_i \quad U_i^+ \subset M_{i+1}$$

$$\varphi_i : (U_i^-, g_{T_i}^i) \xrightarrow{\cong} (U_i^+, g_{T_i}^{i+1})$$

surgery scale $\approx \delta \ll 1$

Theorem (Perelman 2003)

This process can be continued indefinitely.
No accumulation of T_i .



Space-time picture

- Space-time 4-manifold:

$$\mathcal{M}^4 = (M_1 \times [0, T_1] \cup_{\varphi_1} M_2 \times [T_1, T_2] \cup_{\varphi_2} M_3 \times [T_2, T_3] \cup_{\varphi_3} \dots) - \mathcal{S}$$

$$\mathcal{S} = (M_1 \times \{T_1\} - U_1^-) \cup (M_2 \times \{T_1\} - U_1^+) \cup \dots \quad (\text{surgeries points})$$

- Time function: $t: \mathcal{M} \rightarrow [0, \infty)$.

- Time-slice: $\mathcal{M}_t = t^{-1}(t)$

- Time vector field:

∂_t on \mathcal{M} (with $\partial_t \cdot t = 1$).

- Metric g : on the distribution

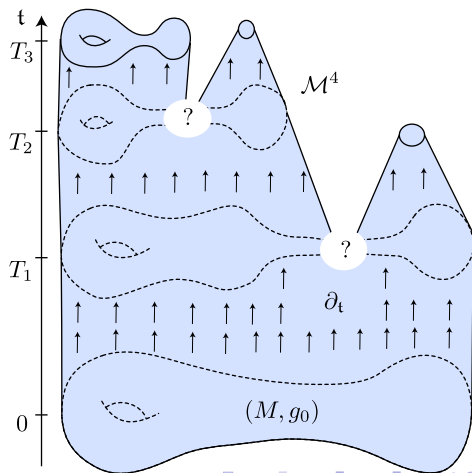
$\{dt = 0\} \subset T\mathcal{M}$

- Ricci flow equation:

$$\mathcal{L}_{\partial_t} g = -2 \text{Ric}_g$$

$(\mathcal{M}, t, \partial_t, g)$ is called a
Ricci flow spacetime.

Note: there are “holes” at scale $\approx \delta$



Space-time picture

The spacetime $(\mathcal{M}, t, \partial_t, g)$

- ... satisfies the ε -canonical neighborhood assumption at scales $(C\delta, r_\varepsilon)$
- ... is $C\delta$ -complete,

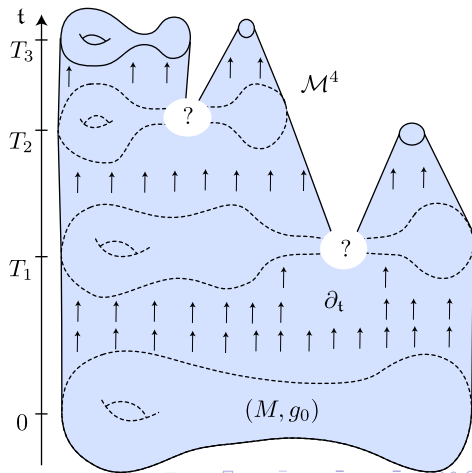
Definition

\mathcal{M} is r_0 -complete if the following is true: Suppose that $\gamma : [0, s_0) \rightarrow \mathcal{M}$ is a curve and:

- $\gamma([0, s_0)) \subset \mathcal{M}_{t_0}$ for some t_0 and $\text{length}_{t_0}(\gamma) < \infty$, OR
- γ is a trajectory of $\pm\partial_t$

Then if $\inf_{s \in [0, s_0)} \rho(\gamma(s)) > r_0$, then $\lim_{s \nearrow s_0} \gamma(s)$ exists.

This implies that $\{\rho \geq r', t \leq T\} \subset \mathcal{M}$ is compact if $r' > r_0$



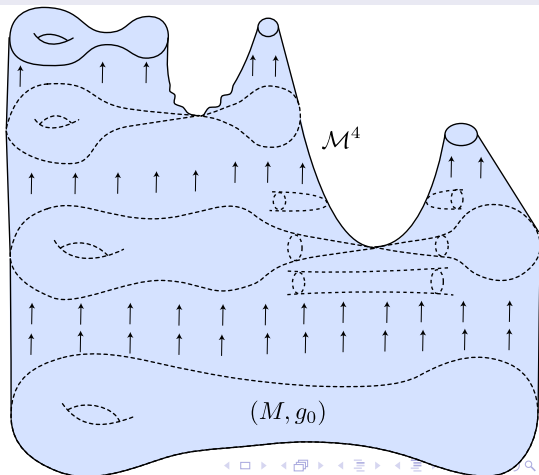
Kleiner, Lott 2014: Compactness theorem and $\delta_i \rightarrow 0 \rightsquigarrow \mathcal{M}^{\delta_i} \rightarrow \mathcal{M}$
 \implies existence of (weak) singular Ricci flow starting from any (M, g_0)

Singular Ricci flow: Ricci flow spacetime \mathcal{M} that:

- is 0-complete (i.e. “surgery scale $\delta = 0$ ”)
- satisfies the ε -canonical neighbhd assumption below some scale $r(\varepsilon)$ for any ε

Remarks:

- \mathcal{M} is smooth everywhere and not defined at singularities
- singular times may accumulate



Theorem (Ba., Kleiner, 2017)

There is a constant $\varepsilon_{\text{can}} > 0$ such that:

Every Ricci flow space-time $(\mathcal{M}, \mathfrak{t}, \partial_{\mathfrak{t}}, g)$ is uniquely determined (up to isometry) by its initial time-slice (\mathcal{M}_0, g_0) , provided that it

- is **0-complete** and
- satisfies the **ε_{can} -canonical neighborhood assumption** below some positive scale.

So it is enough to define singular Ricci flow via ε_{can} -canonical neighborhood assumption for some *universal* ε_{can} .

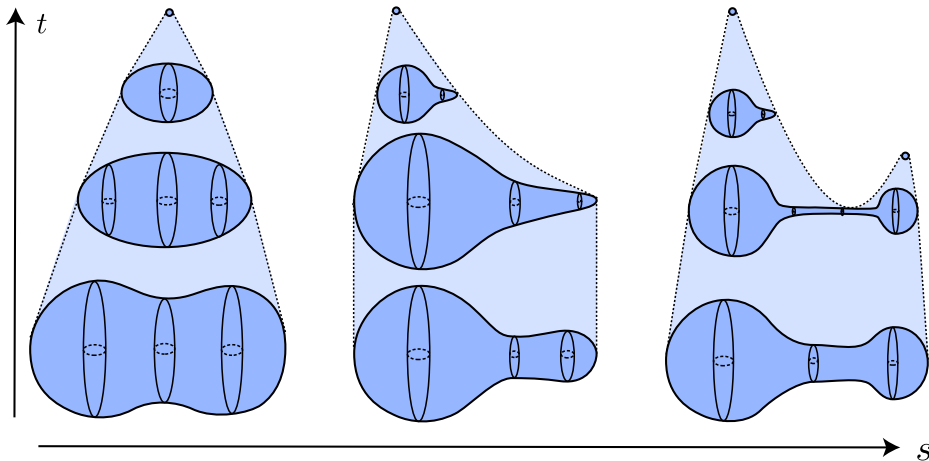
Corollary

For every compact (M^3, g_0) there is a **unique, canonical** singular Ricci flow space-time $(\mathcal{M}, \mathfrak{t}, \partial_{\mathfrak{t}}, g)$ with $\mathcal{M}_0 = (M^3, g_0)$.

Continuity of RF space-times

continuous family of metrics $(g_s)_{s \in [0,1]}$ on M

$\rightsquigarrow \{\mathcal{M}_s\}_{s \in [0,1]}$ canonical RF space-times



Theorem (Ba., Kleiner)

Every continuous family $(g_s)_{s \in \Omega}$ of Riemannian metrics on a compact manifold M^3 gives rise to a “continuous family of Ricci flow space-times”.

More on this later ...

Structure of proof

Theorem (Ba., Kleiner, 2017)

There is a constant $\varepsilon_{\text{can}} > 0$ such that:

Every Ricci flow space-time $(\mathcal{M}, \mathfrak{t}, \partial_{\mathfrak{t}}, g)$ is uniquely determined (up to isometry) by its initial time-slice (\mathcal{M}_0, g_0) , provided that it

- is **0-complete** and
- satisfies the **ε_{can} -canonical neighborhood assumption** below some positive scale.

Structure of proof

- 1 Blow-up analysis of almost singular part (Lectures 1+2)
- 2 Linear stability theory (Lecture 2)
- 3 Construction of comparison map + Spatial Extension Principle (Lecture 3)

Lecture II

- A (Strong) ε -necks
- B Setup of the Toy Case
- C Uniqueness in the non-singular case
- D Local stability analysis

Lecture II.A

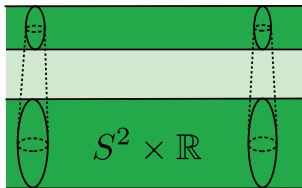
(Strong) ε -necks

Recall: $\rho = (\frac{1}{3}R)^{-1/2}$

shrinking cylinder: $g_{S^2 \times \mathbb{R}, t} = (\frac{2}{3} - 2t)g_{S^2} + g_{\mathbb{R}}$

$$\rho(\cdot, 0) \equiv 1, \quad \rho(\cdot, -1) \equiv 2$$

(M, g) Riemannian manifold



ε -neck (at scale r): $U \subset M$ such that there is a diffeomorphism $\psi : S^2 \times (-\varepsilon^{-1}, \varepsilon^{-1}) \rightarrow U$ with

$$\|r^{-2}\psi^*g - g_{S^2 \times \mathbb{R}, 0}\|_{C^{[\varepsilon^{-1}]}(S^2 \times (-\varepsilon^{-1}, \varepsilon^{-1}))} < \varepsilon$$

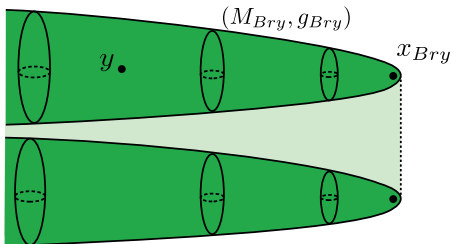
$\psi(S^2 \times \{0\})$ **central 2-sphere**, consisting of **centers** of U

$(M, (g_t))$ Ricci flow

strong ε -neck (at scale r): as before, but

$$\|r^{-2}\psi^*g_{r^2t+t_0} - g_{S^2 \times \mathbb{R}, t}\|_{C^{[\varepsilon^{-1}]}(S^2 \times (-\varepsilon^{-1}, \varepsilon^{-1}) \times [-1, 0])} < \varepsilon$$

Example: Bryant soliton $(M_{Bry}, g_{Bry}, x_{Bry})$



If $d_t(y, x_{Bry}) > C_{Bry}(\varepsilon)$, then (y, t) is a center of a strong ε -neck.

Lemma

For a general RF $(M, (g_t)_{t \in [0, T)})$ and $(y, t) \in M \times [0, T)$ we have:

There is $\varepsilon'(\varepsilon) > 0$ such that if

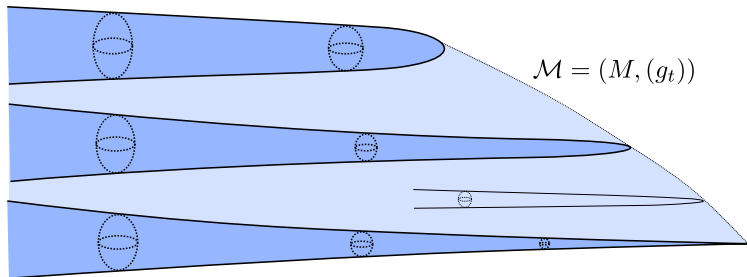
- (y, t) is a center of an ε' -neck and
- the flow satisfies the ε' -canonical neighborhood assumption below scale $\varepsilon^{-1}\rho(y, t)$,

then (y, t) is also a center of a *strong* ε -neck.

Lecture II.B

Setup of the Toy Case

We will only consider Ricci flow spacetimes \mathcal{M} with the following properties:

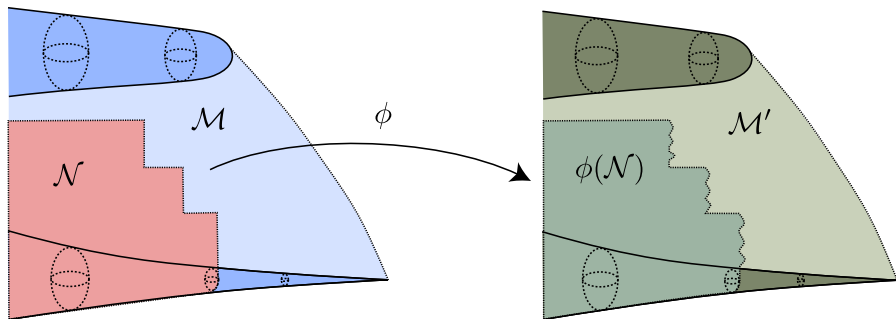


- 1 $\mathcal{M}_{(0,T)}$ comes from a non-singular, conventional RF $(M, (g_t)_{t \in (0,T)})$ that is κ -noncollapsed at scales < 1 and $R > 0$.
- 2 \mathcal{M}_0 can be compactified by adding a single point.
 $\mathcal{M}_0 \cong (M - X, g_0 := \lim_{t \searrow 0} g_t)$ for some $X \subset M$.
- 3 $\rho_{\min}(t) := \min_M \rho(\cdot, t) = \rho(x_t, t)$ is weakly increasing.
- 4 Every $(x, t) \in M \times (0, T)$ with $\rho(x, t) < 1$ is one of the following:
 - a center of a strong ε -neck at scale $\rho(x, t)$
 - locally ε -modeled on $(M_{B_{ry}}, g_{B_{ry}}, y)$ for some $y \in M_{B_{ry}}$ with $d_t(y, x_{B_{ry}}) < C_{B_{ry}}(\varepsilon)$.

(ε will be chosen small in the following)

Strategy

- Let $\mathcal{M}, \mathcal{M}'$ be as before and suppose $\mathcal{M}_0 \cong \mathcal{M}'_0$. Want to show $\mathcal{M} \cong \mathcal{M}'$.
- If we could show that $\mathcal{M}_t \cong \mathcal{M}'_t$ for some $t > 0$, then $\mathcal{M}_{\geq t} \cong \mathcal{M}'_{\geq t}$.
- Construct $\mathcal{N} \subset \mathcal{M}$ (comparison domain) and $\phi : \mathcal{N} \rightarrow \mathcal{M}'$ (comparison map) that is $(1 + \eta)$ -bilipschitz
- Let $\eta \rightarrow 0$ and $\mathcal{N} \rightarrow \mathcal{M}$, limit \rightsquigarrow isometry between $\mathcal{M}, \mathcal{M}'$



Lecture II.C

Uniqueness in an even more basic case:
the non-singular case

Theorem

$$(M, g(0)) \cong (M', g'(0)) \implies (M, g(t)) \cong (M', g'(t))$$

Proof

- **Comparison map:** $\phi : M \rightarrow M'$ such that $\phi^* g'(0) = g(0)$
- **Perturbation:** $h(t) = \phi^* g'(t) - g(t), \quad h(0) \equiv 0$
- **DeTurck's trick:** If ϕ_t^{-1} moves by **harmonic map heat flow**

$$\partial_t \phi_t^{-1} = \Delta_{g'(t), g(t)} \phi_t^{-1},$$

then

$$\partial_t h = \Delta_{g(t)} h + 2 \operatorname{Rm}_{g(t)}(h) + \nabla h * \nabla h + h * \nabla^2 h$$

(Ricci-DeTurck flow)

- Standard parabolic theory: $h(0) \equiv 0 \implies h(t) \equiv 0$ **q.e.d.**

Later:

If $|h(t)| < \eta_{\text{lin}} \ll 1$, then

$$\partial_t h \approx \Delta_{g(t)} h + 2 \operatorname{Rm}_{g(t)}(h) \quad \text{where} \quad (\operatorname{Rm}(h))_{ij} = R_{istj} h_{st}$$

(linearized Ricci-DeTurck flow)

Lecture II.D

Local stability analysis

Linearized Ricci DeTurck flow

(g_t) Ricci flow with $R > 0$ (for simplicity)

(h_t) linearized Ricci DeTurck flow:

$$\partial_t h = \Delta_{g(t)} h + 2 \operatorname{Rm}_{g(t)}(h)$$

Anderson, Chow (2005)

$$\partial_t \frac{|h|}{R} \leq \Delta \frac{|h|}{R} - 2 \frac{\nabla R}{R} \cdot \nabla \frac{|h|}{R}$$

So $\max_M \frac{|h|}{R}(\cdot, t)$ is non-increasing in t .

Proof: $\square = \partial_t - \Delta$

$$\begin{aligned} \square \frac{|h|}{R} &= \frac{1}{R^2} (\square |h| \cdot R - |h| \square R) - 2 \frac{\nabla R}{R} \cdot \nabla \frac{|h|}{R} \\ &\leq \frac{1}{R^2} \left(\frac{2 \operatorname{Rm}(h, h)}{|h|} \cdot R - |h| \cdot 2 |\operatorname{Ric}|^2 \right) - 2 \frac{\nabla R}{R} \cdot \nabla \frac{|h|}{R} \end{aligned}$$

Need

$$\operatorname{Rm}(h, h)R \leq |h|^2 |\operatorname{Ric}|^2$$

Can be checked using an “elementary” computation.

Interpretation

Anderson, Chow (2005)

$\max_M \frac{|h|}{R}$ is non-increasing

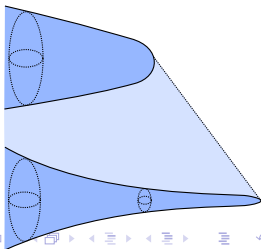
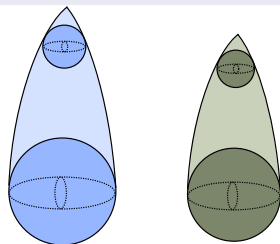
Disadvantage:

- Differences at **macroscopic** scales ($R \approx 1$) may have big effect at **microscopic** scales ($R \gg 1$).

- example: $g(t) = (1 - 4t)g_{S^3}$,
 $g'(t) = (0.9 - 4t)g_{S^3}$,
 $|h|_{g(t)}(t) \sim \frac{0.1}{1 - 4t} \sim R(\cdot, t)$.

Advantage:

- Differences at **microscopic** scales ($R \gg 1$) have little effect at **macroscopic** scales ($R \approx 1$).
- example: Ricci flow regularizing infinitesimal surgery.



Vanishing Theorem

Let $(M, (g_t)_{t \in (-\infty, 0]})$ be a κ -solution and $(h_t)_{t \in (-\infty, 0]}$ a linearized RDTF s.t.

$$|h| \leq CR^{1+\gamma}, \quad \gamma > 0.$$

Then $h \equiv 0$.

Proof: $|h| \leq CR^{1+\gamma} \leq CC'R$. Suppose that $(x_i, t_i) \in M \times (-\infty, 0]$ s.t.

$$\frac{|h|}{R}(x_i, t_i) \xrightarrow{i \rightarrow \infty} \sup_{M \times (-\infty, 0]} \frac{|h|}{R} =: C_0 > 0.$$

Then

$$R^\gamma(x_i, t_i) = \frac{R^{1+\gamma}}{R}(x_i, t_i) \geq \frac{C^{-1}|h|}{R}(x_i, t_i) \xrightarrow{i \rightarrow \infty} C^{-1}C_0 > 0 \quad (*)$$

So $R(x_i, t_i) > c > 0$. After passing to a subsequence

$$(M, (g_{t+t_i})_{t \in (-\infty, 0]}, x_i) \xrightarrow{i \rightarrow \infty} (M_\infty, (g_t^\infty)_{t \in (-\infty, 0]}, x_\infty)$$

$$(h_{t+t_i})_{t \in (-\infty, 0]} \xrightarrow{i \rightarrow \infty} (h_t^\infty)_{t \in (-\infty, 0]}$$

$$|h^\infty| \leq CR^{1+\gamma}, \quad \frac{|h^\infty|}{R} \leq C_0 \quad \text{with equality at } (x_\infty, 0)$$

$$|h^\infty| \leq CR^{1+\gamma}, \quad \frac{|h^\infty|}{R} \leq C_0 \quad \text{with equality at } (x_\infty, 0)$$

Anderson-Chow + strong maximum principle $\implies \frac{|h^\infty|}{R} \equiv C_0$

$$R^\gamma = \frac{R^{1+\gamma}}{R} \geq \frac{C^{-1}|h^\infty|}{R} = C^{-1}C_0^{-1} > 0$$

on $M_\infty \times (-\infty, 0]$.

This is false on any κ -solution.

q.e.d.

- (g_t) RF background
- (h_t) solution to **non-linear** RDTF

$$\partial_t h = \Delta h + 2 \operatorname{Rm}(h) + \nabla h * \nabla h + h * \nabla^2 h$$

- **Observation:** Divide by $0 < a \ll 1$

$$\partial_t \left(\frac{h}{a} \right) = \Delta \left(\frac{h}{a} \right) + 2 \operatorname{Rm} \left(\frac{h}{a} \right) + a \cdot \nabla \left(\frac{h}{a} \right) * \nabla \left(\frac{h}{a} \right) + a \cdot \left(\frac{h}{a} \right) * \nabla^2 \left(\frac{h}{a} \right)$$

- If $a_i \rightarrow 0$ and $\frac{h_i}{a_i} \rightarrow h_\infty$, then (assuming certain derivative bounds)

$$\partial_t h_\infty = \Delta h_\infty + 2 \operatorname{Rm}(h_\infty)$$

(linearized RDTF)

$(g_t)_{t \in [0, T]}$ κ -noncollapsed RF, ε -canonical nbhd assumption below scale 1,
 $(h_t)_{t \in [0, T]}$ (non-linear) RDTF

$$Q := e^{-Ht} \frac{|h|}{R^E}, \quad E > 1$$

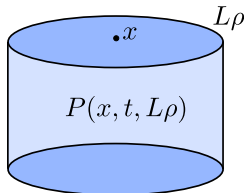
Semi-local maximum principle + Interior decay

For any $\alpha, \kappa > 0$, $E > 1$ there are $H, \varepsilon, \eta, L > 0$ s.t. if

$$|h| \leq \eta \quad \text{on} \quad P = P(x, t, L\rho(x, t)),$$

then

$$Q(x, t) \leq \alpha \sup_P Q. \quad (*)$$



Proof: Fix α, κ, E and argue by contradiction. Choose $H_i, L_i \rightarrow \infty$, $\eta_i, \varepsilon_i \rightarrow 0$.
 Counterexamples $(M_i, (g_t^i)), (h_i)$, $|h_i| \leq \eta_i \rightarrow 0$, $r_i := \rho(x_i, t_i)$.

Opposite of (*): On P_i

$$\alpha e^{-Ht} \frac{|h_i|}{R^E} \leq \alpha \sup_{P_i} Q < Q(x_i, t_i) = e^{-Ht_i} \frac{|h_i|}{R^E}(x_i, t_i)$$

$$\frac{|h_i|}{|h_i|(x_i, t_i)} \leq \alpha^{-1} e^{-H_i(t_i-t)} \frac{R^E}{R^E(x_i, t_i)}$$

$$\frac{|h_i|}{|h_i|(x_i, t_i)} \leq \alpha^{-1} e^{-H_i(t_i-t)} \frac{R^E}{R^E(x_i, t_i)} \quad \text{on } P_i$$

After passing to a subsequence ($r_i = \rho(x_i, t_i)$):

$$(M_i, (r_i^{-2} g_{r_i^2 t + t_i}, x_i)) \xrightarrow{i \rightarrow \infty} (M_\infty, (g_t^\infty)_{t \in (-\infty, 0]}, x_\infty)$$

$$\frac{h_i}{|h_i|(x_i, t_i)} \xrightarrow{i \rightarrow \infty} (h_{\infty, t})_{t \in (-\infty, 0]} \quad (\text{linearized RDTF})$$

Then $|h_\infty|(x_\infty, 0) = \rho(x_\infty, 0) = 1$

$$|h_\infty|(y, t) \leq \lim_{i \rightarrow \infty} 10\alpha^{-1} e^{H_i r_i^2 \cdot t} R^E(y, t)$$

Case $\liminf_{i \rightarrow \infty} r_i > 0$: $|h_\infty|(\cdot, t) \equiv 0$ for $t < 0 \implies h_\infty \equiv 0$

Case $\liminf_{i \rightarrow \infty} r_i = 0$: limit is κ -solution
 $|h_\infty| \leq 10\alpha^{-1} R^E$ Vanishing Thm $\implies h_\infty \equiv 0$
 q.e.d.

Recap

$(g_t)_{t \in [0, T]}$ κ -noncollapsed RF, ε -canonical nbhd assumption below scale 1,
 $(h_t)_{t \in [0, T]}$ (non-linear) RDTF

$$Q := e^{-Ht} \frac{|h|}{RE}, \quad E > 1$$

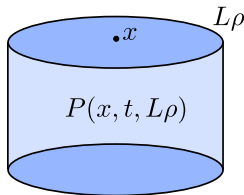
Semi-local maximum principle + Interior decay

For any $\alpha, \kappa > 0$, $E > 1$ there are $H, \varepsilon, \eta, L > 0$ s.t. if

$$|h| \leq \eta \quad \text{on} \quad P = P(x, t, L\rho(x, t)),$$

then

$$Q(x, t) \leq \alpha \sup_P Q. \quad (*)$$



Consequences (and minor generalizations):

- If $Q(\cdot, 0) \leq H^{-1}\bar{Q}$ and $|h| \leq \eta$ on $M \times [0, T]$, then $Q \leq \bar{Q}$ on $M \times [0, T]$.
- If $Q(\cdot, 0) \leq H^{-1}\bar{Q}$ and if \bar{Q} is chosen such that

$$Q \leq \bar{Q} \quad \implies \quad |h| \leq \eta,$$

then $Q \leq \bar{Q}$ and $|h| \leq \eta$.

- Can make η independent of α, κ .

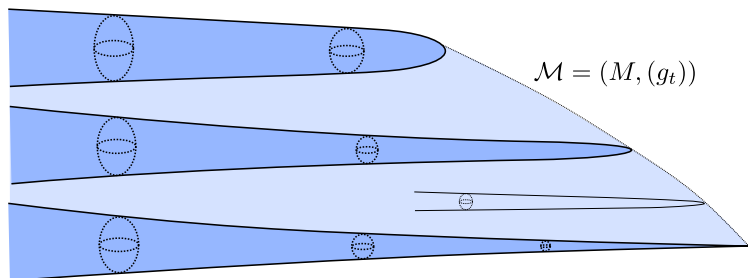
Lecture III

- A Construction of the comparison map
- B The Cap Extension
- C The general case
- D Precise statements of the results + further byproducts of the proof
- E Continuous Dependence

Lecture III.A

Construction of the comparison map

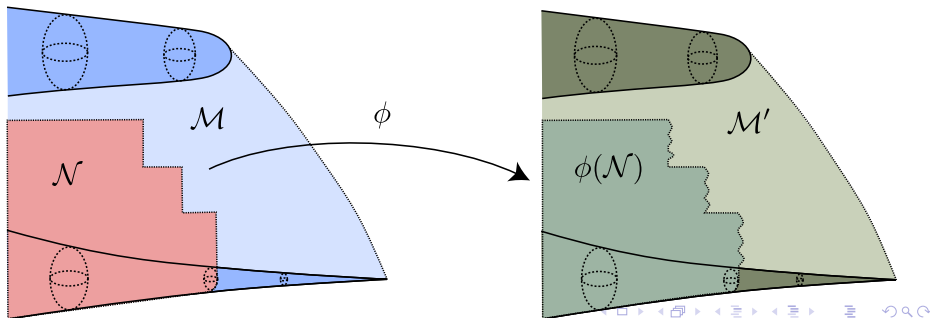
Recap: Toy case



- 1 $M_{(0, T)}$ comes from a non-singular, conventional RF $(M, (g_t)_{t \in (0, T)})$ that is κ -noncollapsed at scales < 1 and $R > 0$.
- 2 M_0 can be compactified by adding a single point.
 $M_0 \cong (M - X, g_0 := \lim_{t \searrow 0} g_t)$ for some $X \subset M$.
- 3 $\rho_{\min}(t) := \min_M \rho(\cdot, t) = \rho(x_t, t)$ is weakly increasing.
- 4 Every $(x, t) \in M \times (0, T)$ with $\rho(x, t) < 1$ is one of the following:
 - a center of a strong ε -neck at scale $\rho(x, t)$
 - locally ε -modeled on $(M_{B_{Ry}}, g_{B_{Ry}}, y)$ for some $y \in M_{B_{Ry}}$ with $d_t(y, x_{B_{Ry}}) < C_{B_{Ry}}(\varepsilon)$.

Recap: Strategy

- Let $\mathcal{M}, \mathcal{M}'$ be as in toy case and s.t. $\mathcal{M}_0 \cong \mathcal{M}'_0$. Want to show $\mathcal{M} \cong \mathcal{M}'$.
- Construct $\mathcal{N} \subset \mathcal{M}$ (comparison domain) and $\phi : \mathcal{N} \rightarrow \mathcal{M}'$ (comparison map) that is $(1 + \eta)$ -bilipschitz and such that ϕ^{-1} locally evolves by harmonic map heat flow
- Let $\eta \rightarrow 0$ and $\mathcal{N} \rightarrow \mathcal{M}$, limit \rightsquigarrow isometry between $\mathcal{M}, \mathcal{M}'$
- Set $h := \phi^* g' - g$ (evolves by non-linear RDTF).
- h can be controlled via semi-local maximum principle far from $\partial\mathcal{N}$



Construction of the comparison domain

- $\delta_n > 0$ and $\lambda = \lambda(\delta_n)$ to be determined later
- Choose $r_{\text{comp}} \ll 1$ (comparison scale)
- $t_j := j \cdot r_{\text{comp}}^2$, $j = 0, \dots, J$
- $t_J = T$
- choose $j_0 \in \{0, \dots, J\}$ minimal s.t. $\rho_{\min}(t_{j_0}) = \min_M \rho(\cdot, t_{j_0}) \geq \lambda r_{\text{comp}}$

Lemma

There is a comparison domain

$$\mathcal{N} = (\mathcal{N}^1 \cup \dots \cup \mathcal{N}^{j_0}) \cup (\mathcal{N}^{j_0+1} \cup \dots \cup \mathcal{N}^J) \subset \mathcal{M}$$

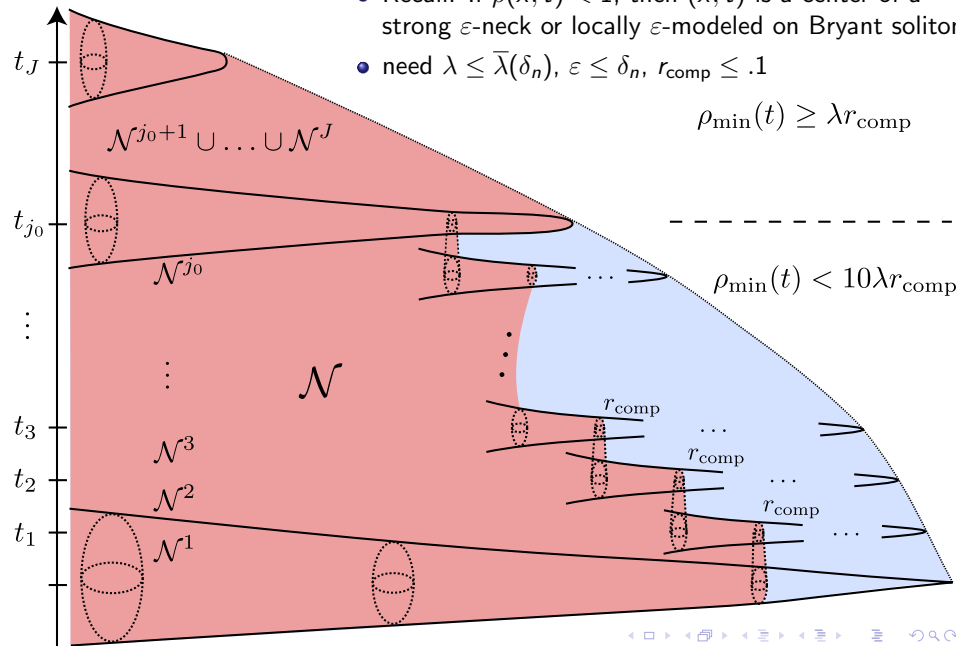
such that

- $\mathcal{N}^j = N_j \times [t_{j-1}, t_j]$, $M \supset N_1 \supset N_2 \supset \dots \supset N_{j_0}$
- $\partial \mathcal{N}_{t_j}^j$ is central 2-sphere of strong δ_n -neck at scale r_{comp}
- $\rho > \frac{1}{2} r_{\text{comp}}$ on $\mathcal{N}^1 \cup \dots \cup \mathcal{N}^{j_0}$
- $\mathcal{N}^j = M \times [t_{j-1}, t_j]$ for $j \geq j_0 + 1$

- $\partial\mathcal{N}_{t_j}^j$ must be central 2-sphere of strong δ_n -neck
- Recall: If $\rho(x, t) < 1$, then (x, t) is a center of a strong ε -neck or locally ε -modeled on Bryant soliton
- need $\lambda \leq \bar{\lambda}(\delta_n)$, $\varepsilon \leq \delta_n$, $r_{\text{comp}} \leq .1$

$$\rho_{\min}(t) \geq \lambda r_{\text{comp}}$$

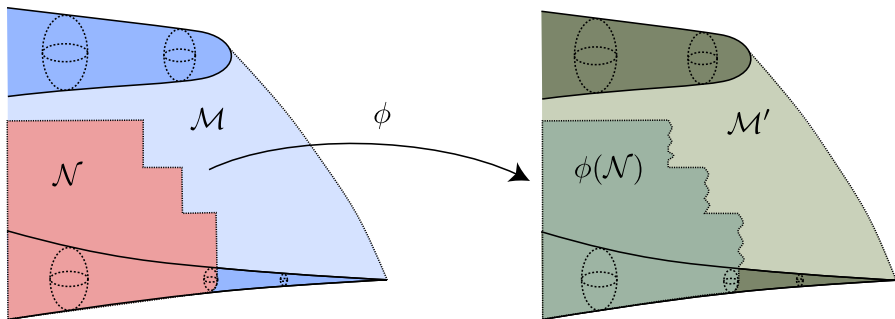
$$\rho_{\min}(t) < 10\lambda r_{\text{comp}}$$



Construction of comparison map for $t \leq t_{j_0}$

Goal: Construct **comparison map** $\phi : \mathcal{N}^1 \cup \dots \cup \mathcal{N}^{j_0} \rightarrow \mathcal{M}'$,
s.t. ϕ^{-1} evolves by **harmonic map heat flow** s.t.

$$|h| = |\phi^* g' - g| \leq \eta$$



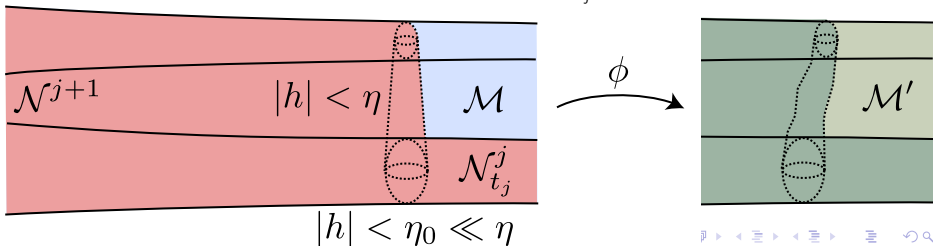
Construction of comparison map for $t \leq t_{j_0}$

Goal: Construct **comparison map** $\phi : \mathcal{N}^1 \cup \dots \cup \mathcal{N}^{j_0} \rightarrow \mathcal{M}'$,
 s.t. ϕ^{-1} evolves by **harmonic map heat flow** s.t.

$$|h| = |\phi^* g' - g| \leq \eta$$

Strategy:

- $\phi|_{\mathcal{N}_0}$ given since $\mathcal{M}_0 \cong \mathcal{M}'_0$
- For each $j = 0, \dots, j_0 - 1$ solve HMHF with initial data $(\phi|_{\mathcal{N}_{t_j}^j})^{-1}$
 (graft half cylinders into $\partial\mathcal{N}^{j+1}$ and its image)
 $\rightsquigarrow \phi|_{\mathcal{N}^{j+1}} : \mathcal{N}^{j+1} \rightarrow \mathcal{M}'$.
- If $\delta_n \leq \bar{\delta}_n(\eta')$ and $|h| < \eta_0(\eta') \ll \eta'$ near $\partial\mathcal{N}_{t_j}^{j+1}$, then $|h| < \eta'$ near $\partial\mathcal{N}^{j+1}$.



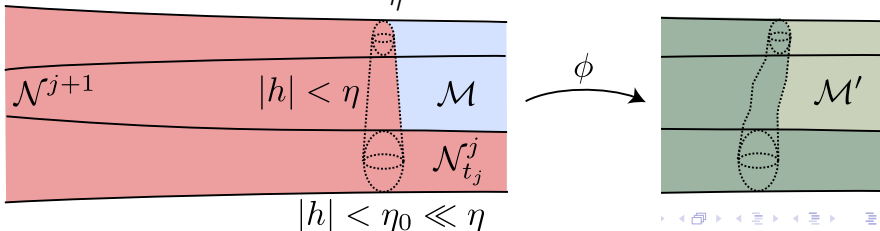
So we need to ensure that :

- ① $|h| < \eta_0(\eta') \ll \eta'$ near $\partial\mathcal{N}_{t_j}^{j+1}$ for some $\eta' \leq \eta$
- ② $|h| \leq \eta$ on \mathcal{N}^{j+1}

Strategy:

- Fix $E \approx 100 > 1$ (TBD) and $Q = e^{-Ht} \frac{|h|}{R^E}$
- Choose $\bar{Q} \approx e^{-HT} \eta r_{\text{comp}}^{2E}$ such that
 - On \mathcal{N}^{j+1} : $Q \leq \bar{Q} \implies |h| < \eta$
 - Near $\partial\mathcal{N}^{j+1}$: $|h| < \frac{e^{-HT}}{100} \eta =: \eta' \implies Q \leq \bar{Q}$
- $Q \leq \bar{Q}$ can be maintained via semi-local maximum principle.
- Moreover: If $d_{t_j}(\partial\mathcal{N}_{t_j}^{j+1}, \partial\mathcal{N}_{t_j}^j) > L(\frac{\eta_0}{\eta})r_{\text{comp}}$, then near $\partial\mathcal{N}_{t_j}^{j+1}$:

$$Q < \frac{\eta_0}{\eta} \bar{Q} \implies |h| < \eta_0$$



$$|h| < \eta_0 \ll \eta$$

Recap: Choice of constants

- Ensure that $\partial\mathcal{N}$ consists of strong δ_n -necks: $\lambda \leq \bar{\lambda}(\delta_n)$, $\varepsilon \leq \delta_n$, $r_{\text{comp}} \leq .1$
- Ensure that $|h| < \eta'$ near $\partial\mathcal{N}^{j+1}$: $\delta_n \leq \bar{\delta}_n(\eta')$, $\eta_0 \leq \bar{\eta}_0(\eta')$
- Apply semi-local maximum principle ($Q \leq \bar{Q}$): $\eta \leq \bar{\eta}$ and $\eta' = \frac{e^{-HT}}{100}\eta$
- Ensure that $d_{t_j}(\partial\mathcal{N}_{t_j}^{j+1}, \partial\mathcal{N}_{t_j}^j) > L(\frac{\eta_0}{\eta})r_{\text{comp}}$ (to show $|h| < \eta_0$ near $\mathcal{N}_{t_j}^{j+1}$):
 $\delta_n \leq \bar{\delta}_n(\frac{\eta_0}{\eta})$

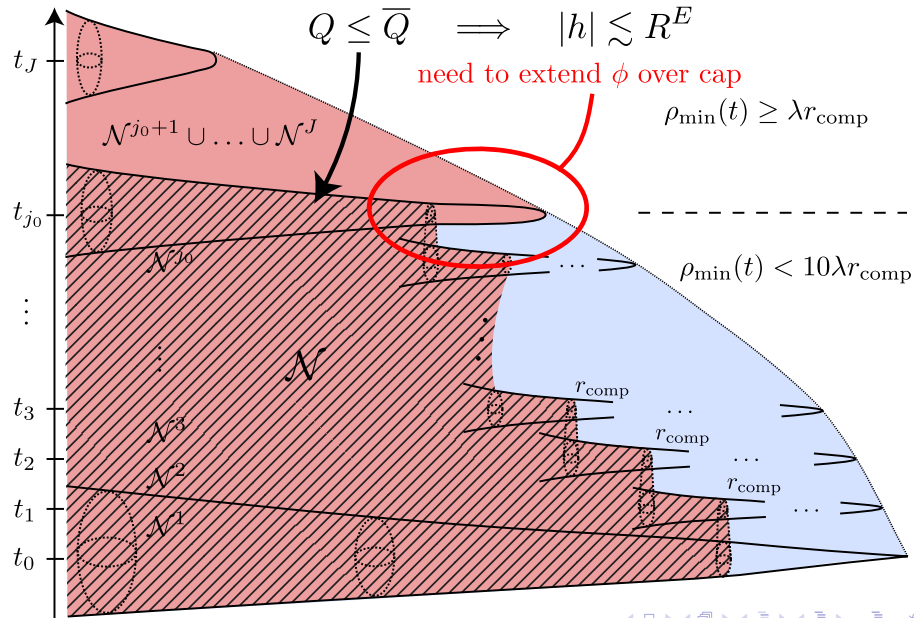
Summary:

$$\begin{array}{ccccccc} \eta & \longrightarrow & \eta' & \longrightarrow & \eta_0 & \longrightarrow & \delta_n & \longrightarrow & \lambda \\ & & & & & & \downarrow & & \\ & & & & & & \varepsilon & & \end{array}$$

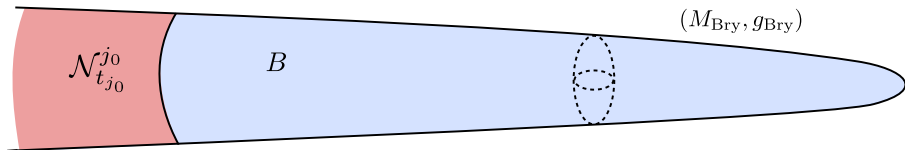
Lecture III.B

The Cap Extension

Construction of comparison map at $t = t_{j_0}$



Cap Extension Problem



- diameter of $B \approx \lambda^{-1} r_{\text{comp}}$
- Precision of ϕ near $\partial \mathcal{N}_{t_{j_0}}^{j_0} \approx \eta_0$
- In order to construct an extension over the cap of precision $\approx \eta$ we would need to have $\eta_0 \leq \bar{\eta}_0(\eta, \lambda)$
- But we have chosen λ depending on $\frac{\eta_0}{\eta}$.

Idea:

- Near $\partial \mathcal{N}_{t_{j_0}}^{j_0}$ we have $Q \leq \bar{Q} \implies |h| \lesssim \eta (R r_{\text{comp}}^2)^E$
- ϕ has much better precision further away from cap
- Extend over larger domain!

Cap Extension

Cantilever Paradox

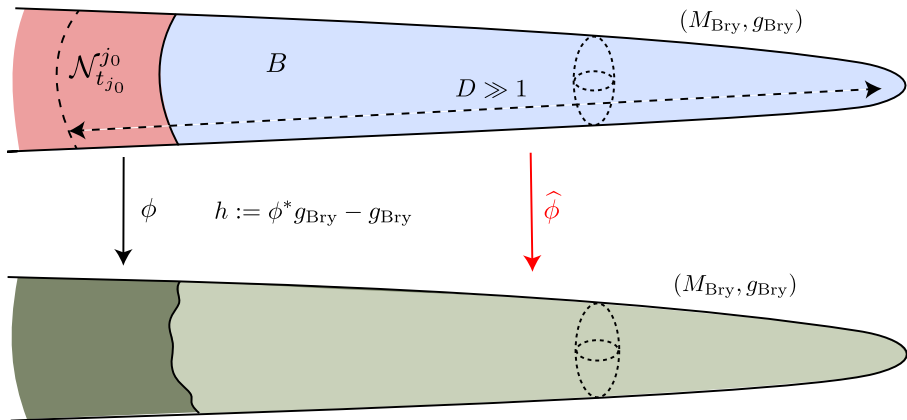
Where do you feel safer?



long cantilever,
good engineering



short cantilever,
sketchy engineering



Rescale s.t. geometry around $B := \mathcal{M}_{t_{j_0}} - \mathcal{N}_{t_{j_0}^{j_0}}$ is close to $(M_{\text{Bry}}, g_{\text{Bry}})$ at scale 1.

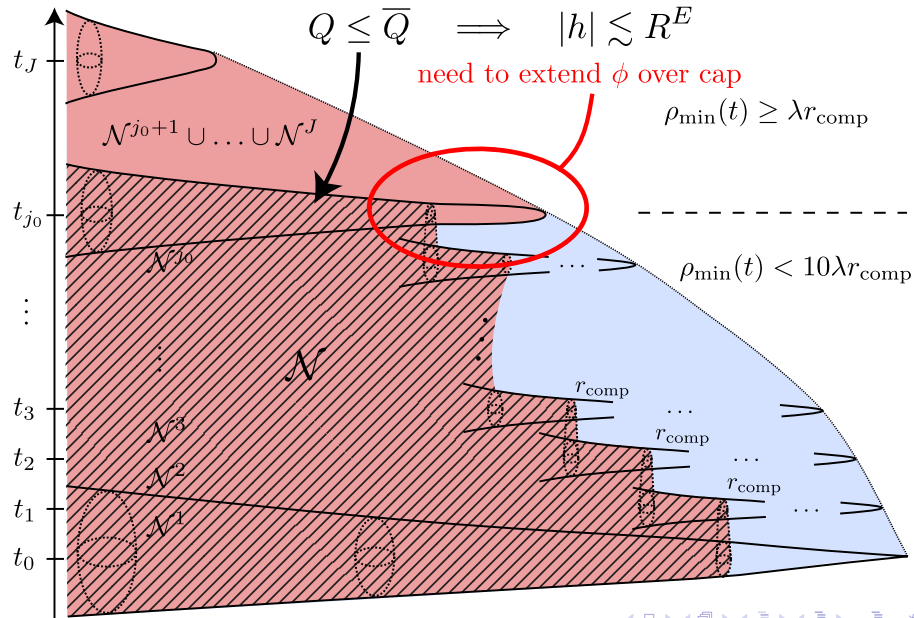
Recall that $Q = e^{-Ht} \frac{|h|}{RE} \leq \bar{Q}$ on \mathcal{N} .

Bryant Extension Principle ("Cap Extension")

If $E \geq 100$ and $D \geq D_0(\beta)$, then we can extend $\phi|_{\mathcal{N}_{t_{j_0}^{j_0}} - B(x_{\text{Bry}}, D)}$ to $\hat{\phi}: \mathcal{M}_{t_{j_0}} \rightarrow M_{\text{Bry}}$ such that

$$|\hat{\phi}^* g_{\text{Bry}} - g_{\text{Bry}}| < \beta R^2$$

Proof, concluded



- Extend $\phi|_{\mathcal{N}_{t_{j_0}^{j_0}}}$ onto $\mathcal{N}_{t_{j_0}^{j_0+1}}$ via **Bryant Extension Principle** (at time t_{j_0}).
- Then at time t_{j_0} :
 - $Q \leq \bar{Q}$ on complement of extension disk
 - $|h| \leq \beta R^2 (\lambda r_{\text{comp}})^4$ on extension disk
- \implies on $\mathcal{M}_{t_{j_0}}$:
 - $Q \leq W\bar{Q}$ for some $W(\lambda) \gg 1$
 - $Q^* = e^{-H^* t} \frac{|h|}{R^2} \leq \bar{Q}^* \approx e^{-H^* T} \eta (\lambda r_{\text{comp}})^4$
- The bound $Q^* \leq \bar{Q}^*$ can be maintained using the semi-local maximum principle (exponent $E^* = 2$) and implies that $|h| \leq \eta$ for times $t \geq t_{j_0}$.
- (By the semi-local maximum principle, the bound $Q \leq W\bar{Q}$ eventually improves to $Q \leq \bar{Q}$.)
- q.e.d.

Lecture III.C

The general case

The general case

Problems that may arise

- Caps may not always be modeled on Bryant solitons (if we don't assume classification of κ -solutions)

Solution: Perform cap extension “at the right time”,
when $\partial_t R \leq 0$ on \mathcal{M} and \mathcal{M}'

- There may be more than one cusp

Solution: Continue the neck and cap extension process after the first cap extension.

- Curvature of the cap may increase again after cap extension (and there may be an accumulation of singular times)

Solution: Perform a “cap removal” when the curvature exceeds a certain threshold.

Ensure that “cap extensions” and “cap removals” are sufficiently separated in space and time such that Q has time to “recover” after a cap extension.

Lecture III.D

Precise statements of the results +
further byproducts of the proof

Uniqueness Theorem

Uniqueness

If $\mathcal{M}, \mathcal{M}'$ are singular Ricci flows and $\phi : (\mathcal{M}_0, g_0) \rightarrow (\mathcal{M}'_0, g'_0)$ is an isometry, then there is a unique extension $\widehat{\phi} : \mathcal{M} \rightarrow \mathcal{M}'$, $\widehat{\phi}|_{\mathcal{M}_0} = \phi$, which is an isometry of Ricci flow spacetimes.

Note:

- $\mathcal{M}, \mathcal{M}'$ could be non-compact or start from singular initial data (need to modify definition of completeness slightly).

The most general consequence

Strong Stability Theorem

If $\delta > 0$, $T < \infty$, $E \geq \underline{E}$, then there are $\varepsilon_{\text{can}}(E), \varepsilon(\delta, T, E) > 0$ such that for all $r \in (0, 1)$ the following holds:

Suppose $\mathcal{M}, \mathcal{M}'$ are Ricci flow spacetimes over $[0, T]$ that are εr -complete and satisfy the ε_{can} -canonical neighborhood assumption at scales $(\varepsilon r, 1)$.

Let $\phi: \mathcal{M}_0 \supset U \rightarrow U' \subset \mathcal{M}'_0$ be a diffeomorphism such that:

- $U \supset \{|\text{Rm}| \leq (\varepsilon r)^{-2}\}$
- $|\phi^* g'_0 - g_0| \leq \varepsilon r^{2E} (|\text{Rm}| + 1)^E$ on U
- “ ϕ does not distort $|\text{Rm}|$ too much” ...

Then there is a time-preserving diffeomorphism

$$\hat{\phi}: \mathcal{M} \supset \hat{U} \rightarrow \hat{U}' \subset \mathcal{M}'$$

such that:

- $\hat{U} \supset \{|\text{Rm}| \leq r^{-2}\}$
- $\hat{\phi}$ evolves by HMHF
- $|\hat{\phi}^* g' - g| \leq \delta r^{2E} (|\text{Rm}| + 1)^E$
- $\hat{\phi}_0 = \phi$ on $U \cap \hat{U}$

Note:

- $\mathcal{M}, \mathcal{M}'$ only need to be defined above scale εr or they may violate the RF equation below that scale.

Consequences:

Convergence of RF with surgery

Fix some closed (M^3, g) . Consider a sequence of RFs with surgery \mathcal{M}^{δ_i} starting from (M, g) , for a sequence of surgery scales $\delta_i \rightarrow 0$. Then (without passing to a subsequence) we have convergence $\mathcal{M}^{\delta_i} \rightarrow \mathcal{M}^\infty$, where \mathcal{M}^∞ is the singular RF starting from (M, g) .

Weak Stability Theorem

For every $\delta, T > 0$ there is an $\varepsilon(\delta, T) > 0$ such that

If $\mathcal{M}, \mathcal{M}'$ are singular RFs and there is a $(1 + \varepsilon)$ -bilipschitz map $\phi : \mathcal{M}_0 \rightarrow \mathcal{M}'_0$, then there is a $(1 + \delta)$ -bilipschitz map

$$\widehat{\phi} : \mathcal{M} \supset \widehat{U} \rightarrow \widehat{U}' \subset \mathcal{M}'$$

such that $\{|\text{Rm}| \leq \delta^{-2}\} \subset \widehat{U}$ and $\widehat{\phi} = \phi$ on $\widehat{U} \cap U$.

Convergence

Consider a sequence of singular Ricci flows \mathcal{M}^i such that there is a sequence of diffeomorphisms $\phi_i : \mathcal{M}_0^\infty \rightarrow \mathcal{M}_0^i$ with

$$\phi_i^* g_0^i \xrightarrow[i \rightarrow \infty]{C_{\text{loc}}^\infty} g_0^\infty.$$

Then there is a sequence of time-preserving diffeomorphisms

$$\hat{\phi}_i : \mathcal{M}^\infty \supset \hat{U}_i \longrightarrow \hat{U}_i' \subset \mathcal{M}^i$$

such that $\hat{U}^i \nearrow \mathcal{M}^\infty$ and

$$\hat{\phi}_i^* g^i \xrightarrow[i \rightarrow \infty]{C_{\text{loc}}^\infty} g^\infty, \quad \hat{\phi}_i^* \partial_t^i \xrightarrow[i \rightarrow \infty]{C_{\text{loc}}^\infty} \partial_t^\infty$$

Question: How to state continuous dependence on initial data?

- 1 Quick and dirty method (next two slides)
- 2 More comprehensive method (later)

Lecture III.E

Continuous dependence

Worldlines and bad points

Worldline: Trajectories γ of ∂_t .

If $\gamma(t_0) = x$, then we write $x(t) := \gamma(t)$.

A point $x \in M$ is called **bad point** if $x(0)$ does not exist (i.e. worldline is incomplete).

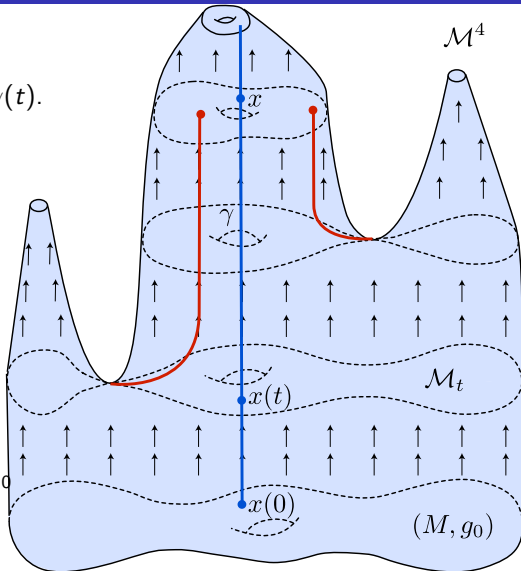
Lemma (Kleiner, Lott)

There are at most **finitely many bad points** in every component $C \subset \mathcal{M}_t$ of every time-slice.

$$W_t := \{x(0) \mid x \in \mathcal{M}_t \text{ good}\} \subset \mathcal{M}_0$$

$\bar{g}_t :=$ pushforward of g_t onto W_t
by flow of $-\partial_t$

Note: $(W_t, \bar{g}_t) \cong (\mathcal{M}_t, g_t) - \text{bad points}$



Continuous dependence — quick and dirty

Recall:

singular Ricci flow \mathcal{M}

$\rightsquigarrow (W_t, \bar{g}_t)_{t \geq 0}$, where $W_t \subset \mathcal{M}_0$ open, decreasing, $(W_0, \bar{g}_0) = (\mathcal{M}_0, g_0)$
and (\bar{g}_t) satisfies the Ricci flow equation

Continuous dependence

Fix M^3 closed. For any Riemannian metric g on M consider a singular Ricci flow $\mathcal{M}^{(M,g)}$ with initial time-slice (M, g) . Then the map

$$g \mapsto \mathcal{M}^{(M,g)} \mapsto (W_t, \bar{g}_t)_{t \geq 0}$$

is continuous in the C_{loc}^∞ -topology. More specifically, if $g^i \rightarrow g^\infty$ in C_{loc}^∞ , then for any $t \geq 0$ we have:

- $W_t^\infty \subset \liminf_{i \rightarrow \infty} W_t^i$, i.e. for any compact $K \subset W_t^\infty$ we have $K \subset W_t^i$ for large i .
- $\bar{g}_t^i \rightarrow \bar{g}_t^\infty$ in C_{loc}^∞ on W_t^∞ .

Note: It may happen that $W_t^i = M$, but $W_t^\infty \subsetneq M$.

Lecture IV

- A Short/Partial Proof of the Generalized Smale Conjecture
- B Continuous families of singular Ricci flows
- C (Long) Proof of both topological conjectures

Lecture IV.A

Short/Partial Proof of the Generalized Smale Conjecture

Setup

Assume $M = S^3/\Gamma$, where $\Gamma \neq 1, \mathbb{Z}_2$ and assume $\text{Diff}(S^3) \simeq O(4)$ (Hatcher)

Goal:

Theorem

$\text{Met}_{K \equiv 1}(M)$ is contractible
(consequently $\text{Diff}(M) \simeq \text{Isom}(M)$)

“Proof”:

- **Hope:** Construct retraction

$$* \simeq \text{Met}(M) \longrightarrow \text{Met}_{K \equiv 1}(M)$$

- **Strategy:**

$$\text{Met}(M) \longrightarrow \{\text{“space of singular RFs”}\} \longrightarrow \text{Met}_{K \equiv 1}(M)$$

- **Question** How to construct the second map?

There are $T_g^1 < T_g^2$ such that:

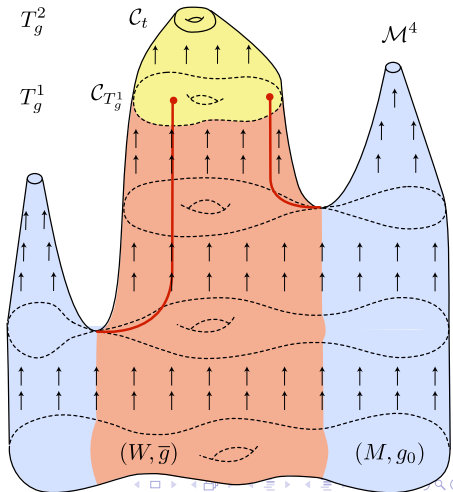
- for every $t \in [T_g^1, T_g^2)$ there is a unique component $\mathcal{C}_t \subset \mathcal{M}_t$ with $\mathcal{C}_t \approx M$.
- (\mathcal{C}_t, g_t) converges to a round metric as $t \nearrow T_g^2$ (modulo rescaling).
(because $M \neq S^3, \mathbb{R}P^3$!!)

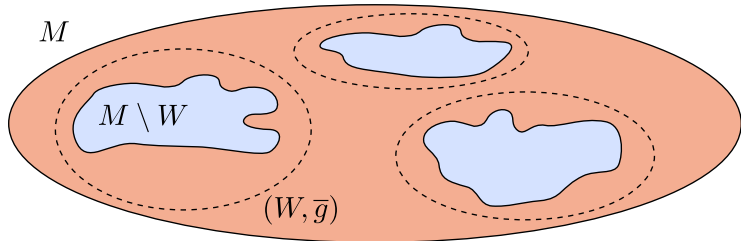
Let $W \subset W_t \subset M$ be the component corresponding to \mathcal{C}_t for $t \in [T_g^1, T_g^2)$.

Recall: $\bar{g}_t :=$ pushforward of g_t onto W by flow of $-\partial_t$

$$\bar{g}_t|_W \xrightarrow[t \nearrow T_g^2]{} \bar{g} \text{ modulo rescaling} \\ (K_{\bar{g}} \equiv 1)$$

$(W, \bar{g}) \cong S^3/\Gamma - \{q_1, \dots, q_N\}$
(q_1, \dots, q_N correspond to bad points)





This process describes a **continuous, canonical** map

$$\begin{array}{ccccc} \text{Met}(M) & \longrightarrow & \{\text{"space of singular RFs"}\} & \longrightarrow & \text{PartMet}_{K \equiv 1}(M) \\ g & \longmapsto & \mathcal{M}^{(M, g)} & \longmapsto & (W, \bar{g}) \end{array}$$

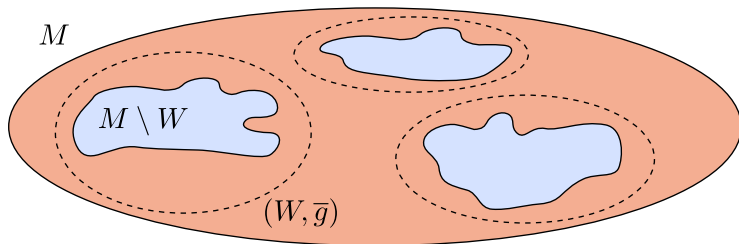
where $\text{PartMet}_{K \equiv 1}(M)$ consists of pairs (W, \bar{g}) such that:

- $W \subset M$ open, \bar{g} is a Riemannian metric on W
- (W, \bar{g}) is isometric to the round punctured S^3/Γ
- $M - W$ can be covered finitely many, pairwise disjoint disks

If $K_g \equiv 1$, then $(W, \bar{g}) = (M, g)$.

Topology on $\text{PartMet}_{K \equiv 1}(M)$: C_{loc}^∞ -convergence on compact subsets of W
(not Hausdorff)

Proof that $\pi_k(\text{Met}_{K \equiv 1}(M)) = 0$

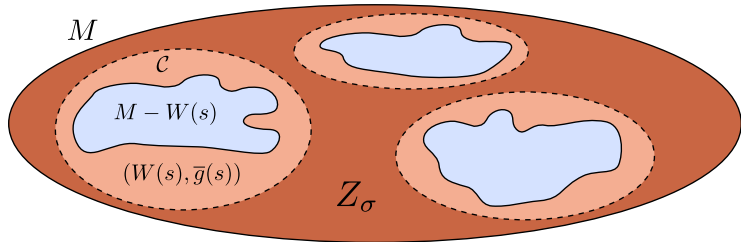


- Consider continuous map $g : S^k \rightarrow \text{Met}_{K \equiv 1}(M)$.
- Extend to $\tilde{g} : D^{k+1} \rightarrow \text{Met}(M)$, $\tilde{g}|_{S^k = \partial D^{k+1}} = g$.
- Previous slide \rightsquigarrow continuous map $D^{k+1} \rightarrow \text{PartMet}_{K \equiv 1}(M)$, given by

$$(W(s), \bar{g}(s)) \in \text{PartMet}_{K \equiv 1}(M), \quad s \in D^{k+1}$$

such that $(W(s), \bar{g}(s)) = (M, g(s))$ for $s \in \partial D^{k+1}$.

- **Goal:** Replace $\bar{g}(s)$ with a $K \equiv 1$ metric on each disk covering $M - W(s)$, in a continuous fashion.



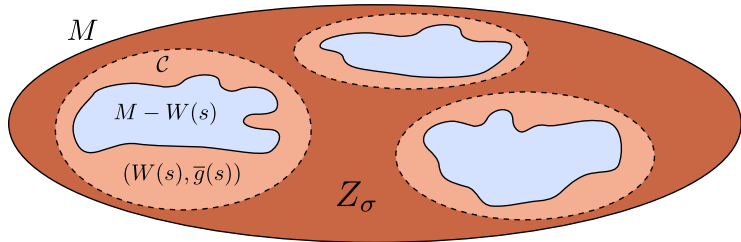
Lemma

We can find a triangulation on D^{k+1} and for each simplex $\sigma \subset D^{k+1}$ a compact subset $Z_\sigma \subset M$ such that the following holds:

- ① $Z_\sigma \subset W(s)$ for all $s \in \sigma$
- ② $M \setminus \text{Int } Z_\sigma$ consists of finitely many disks
- ③ If $\sigma_1 \subsetneq \sigma_2$, then $Z_{\sigma_2} \subset \text{Int}(Z_{\sigma_1})$.
- ④ $Z_\sigma = M$ if $\sigma \subset \partial D^{k+1}$

Proof

- Recall that $(W(s_\sigma), \bar{g}(s_\sigma)) \cong S^3/\Gamma - \{q_1, \dots, q_N\}$ for some (fixed) $s_\sigma \in \sigma$
- Let Z_σ correspond to S^3/Γ minus subcollection of $\{B(q_i, r_{\dim \sigma})\}$, where $r_j = 10^j r_0 \ll 1$



Proceed by induction over $\dim \sigma$:

- **Goal:** Find a continuous family of $K \equiv 1$ metrics $(\hat{g}_\sigma(s))_{s \in \sigma}$ that extend $\bar{g}(s)$ over the missing disks of Z_σ .
- Fix $\sigma \subset D^{k+1}$ and disk $\mathcal{C} \subset M \setminus \text{Int } Z_\sigma$.
- Conditions on $\hat{g}_\sigma(s)|_{\mathcal{C}}$:
 - 1 If $s \in \partial\sigma$: $\hat{g}_\sigma(s)|_{\mathcal{C}} = \hat{g}_{\sigma'}(s)|_{\mathcal{C}}$ for $s \in \sigma' \subset \partial\sigma$
 - 2 Near $\partial\mathcal{C}$: $\hat{g}_\sigma(s) = \bar{g}(s)$

Main tool (for $\sigma \approx D^{j+1}$)

Lemma

Let $A = A(1 - \varepsilon, 1) \subset D(1) \subset \mathbb{R}^3$ and

$$h : D^{j+1} \longrightarrow \text{Met}_{K \equiv 1}(A),$$

$$h_0 : \partial D^{j+1} \longrightarrow \text{Met}_{K \equiv 1}(D(1))$$

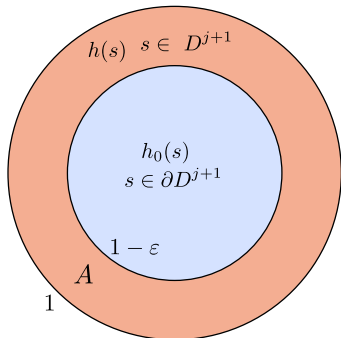
be continuous such that:

- $h_0(s)|_A = h(s)$ for all $s \in \partial D^{j+1}$.
- $(A, h(s))$ embeds into the round sphere for all $s \in D^{j+1}$.

Then, after shrinking ε , there is a continuous map

$$\bar{h} : D^{j+1} \longrightarrow \text{Met}_{K \equiv 1}(D(1))$$

with $\bar{h}(s)|_A = h(s)$ for all $s \in D^{j+1}$
and $\bar{h}(s) = h_0(s)$ for all $s \in \partial D^{j+1}$.



Proof: $\text{Diff}(S^3) \simeq O(3)$ (Hatcher's Theorem) $\implies \text{Diff}(D^3_{\text{rel}} \partial D^3) \simeq 1$

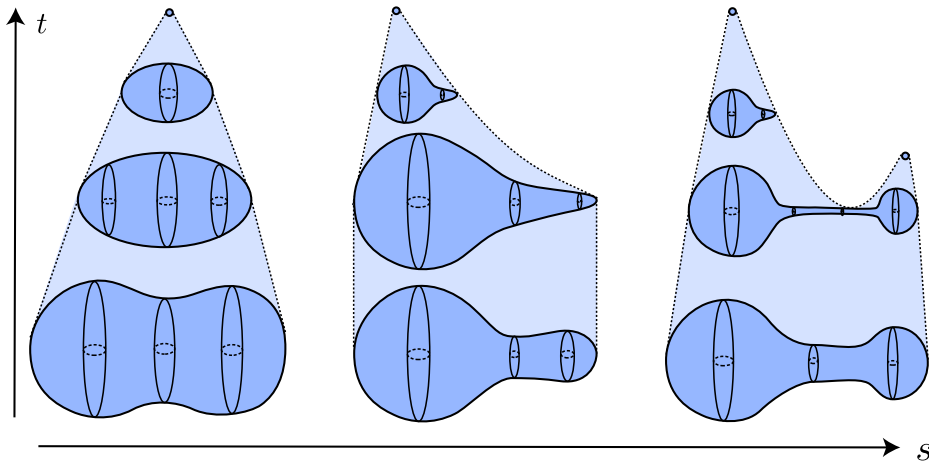
Lecture IV.B

Continuous families of singular Ricci flows

Continuity of RF space-times

continuous family of metrics $(g^s)_{s \in [0,1]}$ on M

$\rightsquigarrow \{\mathcal{M}^s\}_{s \in [0,1]}$ singular Ricci flows



Continuous families of (in-complete) Riemannian manifolds

Note: For fixed t , the family (\mathcal{M}_t^s, g_t^s) is “continuous”,
but topology may change

Example: $\pi : \mathbb{R}^3 - \{0\} \longrightarrow \mathbb{R}, \quad (x, y, z) \mapsto z$

$$M_s := \pi^{-1}(s) = \begin{cases} \mathbb{R}^2 - \{0\} & \text{if } s = 0 \\ \mathbb{R}^2 & \text{else} \end{cases} \quad g_s := \text{Euclidean metric on } M_s$$

Definition

A **continuous family of manifolds** over a topological space X is given by:

- 1 A collection of smooth manifolds $\{M_s^n\}_{s \in X}$
- 2 A **topology** on $Y := \bigsqcup_{s \in X} M_s$ that restricts to the topology on each $M_s \subset Y$, such that the standard projection $\pi : Y \rightarrow X$ is a continuous topological submersion.
- 3 A maximal collection of **charts**

$$\{\phi_{i,s} : V_i \longrightarrow M_s\}_{s \in U_i}, \quad U_i \subset X \text{ open}, \quad V_i = \text{smooth manifold}$$

such that:

- Each $\phi_i : U_i \times V_i \rightarrow Y$ is a homeomorphism onto its open image
- **Compatibility condition:**

$$\phi_{j,s}^{-1} \circ \phi_{i,s} : V_i \supset V'_{ij,s} \longrightarrow V_j$$

consists of smooth maps that depend continuously on s in the C_{loc}^∞ -topology for all i .

A family of Riemannian metrics $\{g_s\}_{s \in X}$ is called **transversely continuous** if $\phi_{i,s}^* g_s$ depends continuously on s in the C_{loc}^∞ -topology.

Definition

A **continuous family of Ricci flow spacetimes** is given by a continuous family of spacetime manifolds $\{\mathcal{M}^s\}_{s \in X}$ such that g^s, t^s, ∂_t^s are transversely continuous.

Continuity of singular Ricci flows

Let M^3 be closed and $(g^s)_{s \in X}$ be a family of Riemannian metrics that depends continuously on s in the C_{loc}^∞ -topology. Choose singular Ricci flows \mathcal{M}^s starting from (M, g^s) for each $s \in X$.

Then $\{\mathcal{M}^s\}_{s \in X}$ can be equipped with a unique structure of a continuous family of Ricci flow spacetimes with the property that the family $\{\mathcal{M}_0^s\}_{s \in X}$ is the trivial family given by $M \times X$.

Note: For any $t \geq 0$, this induces a structure of continuous family of 3-manifolds on $\{\mathcal{M}_t^s\}_{s \in X}$ and the family $\{g_t^s\}_{s \in X}$ is transversely continuous.

Lecture IV.C

(Long) Proof of both topological conjectures

Rounding singular Ricci flows

Observation: If \mathcal{M} is a singular Ricci flow and $\rho(x) \ll 1$, then x is locally ε -modeled on the final time-slice of a κ -solution, which is either round or rotationally symmetric.

Rounding Lemma

Given a continuous family of singular Ricci flows $\{\mathcal{M}^s\}_{s \in X}$ and some $\delta > 0$, there are transversely continuous tensor fields $\{g^{',s}\}_{s \in X}$, $\{\partial_t^{',s}\}_{s \in X}$ such that the family

$$\mathcal{M}^{',s} = (\mathcal{M}^s, t^s, g^{',s}, \partial_t^{',s})$$

forms a continuous family of “rounded, singular almost Ricci flows”:

- All properties of singular Ricci flows hold, except for the precise Ricci flow equation, which is replaced by an almost Ricci flow equation.
- $|g^s - g^{',s}|, |\partial_t^s - \partial_t^{',s}| < \delta$
- At small curvature scales, $g^{',s}$ is locally **precisely** round or rotationally symmetric and the flow of $\partial_t^{',s}$ preserves these symmetries.

Proof: Technical ...

Theorem (Ba., Kleiner 2019)

$\text{Met}_{\text{PSC}}(M)$ and $\text{Met}_{K \equiv 1}(M)$ are either contractible or empty.

Recall from 2D proof ($\pi_k(\text{Met}\dots(M)) = 0$):

- Given $(h_{s,0})_{s \in D^{k+1}}$, PSC or $K \equiv 1$ for $s \in \partial D^{k+1}$
- Need to extend to homotopy $(h_{s,t})_{s \in D^{k+1} \times [0,1]}$ that is PSC or $K \equiv 1$ for $(s,t) \in (\partial D^{k+1} \times [0,1]) \cup (D^{k+1} \times \{1\})$.
- This time: $(h_{s,0})_{s \in D^{k+1}} \rightsquigarrow$ cont. family of rounded, singular almost RFs $(\mathcal{M}'^s)_{s \in D^{k+1}}$

Remaining conversion problem: Given a continuous family of rounded sing. RFs $\{\mathcal{M}'^s\}_{s \in X}$, find a “similar” continuous family of metrics $(h_{s,t})_{s \in X, t \in [0,1]}$ s.t.:

- 1 $(M, h_{s,0}) \cong (\mathcal{M}'^s, g_0^s)$.
- 2 $h_{s,1}$ has $K \equiv 1$ (or PSC).
- 3 If \mathcal{M}'^s has $K \equiv \text{const}$ (or PSC), then so does $h_{s,t}$ for all $t \in [0,1]$.

Condition 2 can be reduced to: $h_{s,1}$ is conformally flat

Conversion Problem: Given $\{\mathcal{M}'^s\}_{s \in X}$, find continuous $(h_{s,t})_{s \in X, t \in [0,1]}$ on M :

- ① $(M, h_{s,0}) \cong (\mathcal{M}'^s_0, g^s_0)$.
- ② $h_{s,1}$ is conformally flat.
- ③ If \mathcal{M}'^s has $K \equiv \text{const}$, then so does $h_{s,t}$ for all $t \in [0,1]$.

“Proof by backwards induction over time:”


- Fix $T \geq 0$ (large)
- Solve conversion problem such that ②, ③ hold and instead of ①:

$$(M, h_{s,0}) \cong (\mathcal{M}'^s_T, g^s_T) \quad (*_T)$$

- Deform $(h_{s,t})$ such that $(*_T - \tau)$, ②, ③ hold.
- Repeat until $T = 0$.

Problem: The topology of \mathcal{M}'^s_T may change as we vary s .

“Partial homotopy at time T ”:

- Notion simulating $(*_T)$, ②, ③.
- If $T \gg 0$, then \exists empty partial homotopy at time T .
- **Construction moves:** partial homotopy at time $T \rightsquigarrow$ partial homotopy at time $T - \tau$
- A partial homotopy at time $T = 0$ induces the desired family $(h_{s,t})$ with ①-③ 

Partial homotopy at time T (simplified definition):

Fix a simplicial decomposition of X . For each simplex $\sigma \subset X$ choose:

- a continuous family of cpt domains $(Z_s^\sigma \subset \mathcal{M}_T^{l,s})_{s \in \sigma}$.
- a continuous family of Riemannian metrics $(h_{s,t}^\sigma)_{s \in \sigma, t \in [0,1]}$ on (Z_s^σ) .

such that $(*_T)$, ②, ③ hold and:

- **Compatibility:** If $s \in \tau \subset \sigma$, then $Z_s^\sigma \subset Z_s^\tau$ and $h_{s,t}^\tau = h_{s,t}^\sigma$ on Z_s^σ .
 - **Largeness of the domains:** $\rho \ll 1$ on $\mathcal{M}_T^s - Z_s^\sigma$ (\Rightarrow round or rot. symmetric)
 - **“Contractible ambiguity”:** $h_{s,t}^\tau$ is round or rotationally symmetric on any complement of the form $Z_s^\tau \setminus Z_s^\sigma$.
-
- If $T \gg 0$, then we can choose $Z_s^\sigma = \emptyset$ (trivial partial homotopy).
 - If $T = 0$, $Z_s^\sigma = \mathcal{M}_0^s$, then part. homotopy induces the desired $(h_{s,t})_{s \in X, t \in [0,1]}$

Modification Moves:

- Passing to a simplicial refinement.
- Enlarging some (Z_s^σ) by a family of round or rot. symmetric subsets.
- Shrinking some (Z_s^σ) by removing a family of disks. (hard!)
- Reducing T to $T - \tau$ if (Z_s^σ) stay away from almost singular parts.